

$$\Rightarrow \Gamma_{11}^1 = \frac{\begin{vmatrix} \frac{1}{2} E_1 & F \\ F_1 - \frac{1}{2} E_2 & G \end{vmatrix}}{EG - F^2}$$

$$\Gamma_{11}^2 = \frac{\begin{vmatrix} E & \frac{1}{2} E_1 \\ F & F_1 - \frac{1}{2} E_2 \end{vmatrix}}{EG - F^2}$$

Alors $\frac{1}{2} \bar{e}_2 = b_{12} \cdot f_1 = \Gamma_{12}^1 \cdot E + \Gamma_{12}^2 \cdot F$

$$\frac{1}{2} G_2 = b_{12} \cdot b_2 = \Gamma_{12}^1 \cdot F + \Gamma_{12}^2 \cdot G$$

$$\Rightarrow \Gamma_{12}^1 = \frac{1}{2} \frac{\begin{vmatrix} E_2 & F \\ G_2 & G \end{vmatrix}}{EG - F^2}$$

$$\Gamma_{12}^2 = \frac{1}{2} \frac{\begin{vmatrix} E & E_2 \\ F & G_2 \end{vmatrix}}{EG - F^2}$$

Finalment, $F_2 - \frac{1}{2} G_1 = b_{22} \cdot b_1 = \Gamma_{22}^1 \cdot E + \Gamma_{22}^2 \cdot F$

$$\frac{1}{2} G_2 = b_{22} \cdot b_2 = \Gamma_{22}^1 \cdot F + \Gamma_{22}^2 \cdot G$$

$$(F_2 = (b_1 \cdot b_2)_2 = b_{12} \cdot b_2 + b_1 \cdot b_{22} = \frac{1}{2} G_1 + b_1 \cdot b_{22})$$

$$\Rightarrow \Gamma_{22}^1 = \frac{\begin{vmatrix} F_2 - \frac{1}{2} G_1 & F \\ \frac{1}{2} G_2 & G \end{vmatrix}}{EG - F^2}$$

$$\Gamma_{22}^2 = \frac{\begin{vmatrix} E & F_2 - \frac{1}{2} G_1 \\ F & \frac{1}{2} G_2 \end{vmatrix}}{EG - F^2}$$

(d) E_j Sup. $F=0$ (v.g. mp. de révolution)

$$\Rightarrow \Gamma_{11}^1 = \frac{1}{2} \frac{E_1 G}{EG} = \frac{E_1}{2E}$$

$$\Gamma_{11}^2 = \frac{-1}{2} \frac{E \cdot \bar{E}_2}{EG} = \frac{-E_2}{2G}$$

$$\Gamma_{12}^1 = \frac{E_2}{2G}$$

$$\Gamma_{12}^2 = \frac{1}{2} \frac{G_1}{G}$$

$$\Gamma_{22}^1 = \frac{-G_1}{2E}$$

$$\Gamma_{22}^2 = \frac{G_2}{2G}$$

Teorema (Gauss) $S_1, S_2 \subseteq \mathbb{R}^3$ superficies

$f: S_1 \rightarrow S_2$ isometría

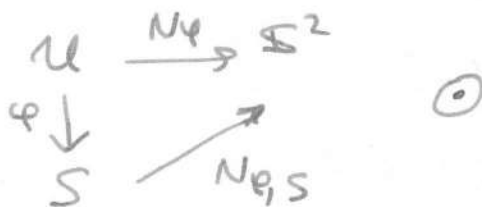
Entonces $K_{S_1}(x) = K_{S_2}(f(x))$, $\forall x \in S_1$

($K_S: S \rightarrow \mathbb{R}$ curvatura de Gauss de S)

Def Sea $U \xrightarrow{\varphi} \mathbb{R}^3$ parametrización regular
 $U \subseteq \mathbb{R}^2$, $S = \varphi(U)$

$$\varphi_1 = \frac{\partial \varphi}{\partial u_1}, \quad \varphi_2 = \frac{\partial \varphi}{\partial u_2}, \quad N_\varphi := \frac{\varphi_1 \times \varphi_2}{|\varphi_1 \times \varphi_2|} : U \rightarrow \mathbb{S}^2$$

Def $N_{\varphi, S} := N_\varphi \circ \varphi^{-1}$



① Sea $V \xrightarrow{\sigma} U$ difeo ($U, V \subseteq \mathbb{R}^2$ abiertos conexos)

$$\begin{array}{ccc}
 V & \xrightarrow{\sigma} U & \xrightarrow{\varphi} \mathbb{R}^3 \\
 \searrow \eta & \nearrow & \\
 & &
 \end{array}
 \quad \eta = \varphi \circ \sigma$$

Entonces $N_{\varphi, S} \circ \eta = \pm N_{\eta, S}$

dem: ejercicio.

Def Para $p \in S$, $\sigma_{f_\varphi}(p): TS(p) \rightarrow T\mathbb{S}^2(N_{\varphi, S}(p))$

$$\sigma_{f_\varphi}(p) := dN_{\varphi, S}(p) = TS(p)$$

$$\textcircled{1} \Rightarrow \sigma_{f_\varphi}(p) = \pm \sigma_{f_\eta}(p)$$

$$\Rightarrow \det \sigma_{f_\varphi}(p) = \det \sigma_{f_\eta}(p)$$

$$:= K_S(p)$$

$\Rightarrow K_S: S \rightarrow \mathbb{R}$ bien definida.

(2) $p = \varphi(u), u \in \mathcal{U}$

$$T\mathcal{U}(u) = \mathbb{R}^2 \xrightarrow{dN_p(u)} TS(p) \quad (\text{aplicando derivada en } \odot)$$

$$\begin{array}{ccc} & & \nearrow \sigma_p(p) \\ d\varphi(u) \downarrow & & \\ & TS(p) & \end{array}$$

vimos: $B = \{e_1, e_2\}$ $a_p = [dN_p]_B$ (en $p = \varphi(u)$)

$$= -[II_p] \cdot [I_p]^{-1}$$

donde $[I_p] = \begin{bmatrix} E_p & F_p \\ F_p & G_p \end{bmatrix}$, $E_p = \varphi_1 \cdot \varphi_1$, $F_p = \varphi_1 \cdot \varphi_2$
 $G_p = \varphi_2 \cdot \varphi_2$

$[II_p] = \begin{bmatrix} e_p & f_p \\ f_p & g_p \end{bmatrix}$, $e_p = \varphi_{11} \cdot N_p$, $f_p = \varphi_{12} \cdot N_p$
 $g_p = \varphi_{22} \cdot N_p$

$$\Rightarrow K_S \circ \varphi = \det a_p = \frac{e_p \cdot g_p - f_p^2}{E_p \cdot G_p - F_p^2}$$

(3) (lema de Gauss) $K_S \circ \varphi$ se puede expresar como $K(E_p, F_p, G_p, (E_p)_1, (E_p)_2, \dots)$
 K expresión explícita, no depende de φ .

$$\textcircled{4} \quad \begin{array}{ccc} S_1 & \xrightarrow{f} & S_2 \\ \varphi_1 \uparrow & & \uparrow \varphi_2 \\ U_1 & \xrightarrow{\bar{f}} & U_2 \end{array} \quad \textcircled{*}$$

$$U_1, U_2 \subseteq \mathbb{R}^2$$

φ_1, φ_2 p.r.

$$S_i = \varphi_i(U_i)$$

\bar{f} difeo.

$$\bar{f} = \varphi_2^{-1} \circ f \circ \varphi_1$$

Entonces:

$$i) [I_{\varphi_1}] = J(\bar{f})^t \cdot [I_{\varphi_2}] \circ \bar{f} \cdot J(\bar{f}) \Leftrightarrow f \text{ isometría}$$

Oe: lo vimos

ii) En particular, si S_1, S_2 están parametrizados por el mismo abierto $U_1 = U_2 = U$, $\bar{f} = \text{id}_U$

$$S_1 \xrightarrow{f} S_2 \quad \text{entonces}$$

$$\varphi_1 \uparrow \quad U \quad \uparrow \varphi_2$$

$$f \text{ isometría} \Leftrightarrow [I_{\varphi_1}] = [I_{\varphi_2}]$$

(φ_1, φ_2 tienen mismos E, F, G)

iii) Si S_1, S_2 son isométricos, existen $U \xrightarrow{\varphi_1} S_1, U \xrightarrow{\varphi_2} S_2$ como en ii).

En efecto, dada f como en $\textcircled{4}$

$$\bar{f} \text{ difeo} \Rightarrow \varphi_2 = \varphi_2 \circ \bar{f} : U_1 \rightarrow S_2 \text{ p.r.}$$

$$\Rightarrow \begin{array}{ccc} S_1 & \xrightarrow{f} & S_2 \\ \varphi_1 \uparrow & & \uparrow \varphi_2 \\ U_1 = U & & U_2 \end{array}$$

es como se buscaba.

⑤ Com le matricul de ④,

$$④ \text{ ii) } \Rightarrow [I_{\varphi_1}] = [I_{\varphi_2}]$$

$$\Rightarrow \textcircled{3} \quad K_{S_1} \circ \varphi_1 = K_{S_2} \circ \varphi_2$$

$$\Rightarrow \varphi_2 = f \circ \varphi_1 \quad K_{S_1} \circ \varphi_1 = K_{S_2} \circ f \circ \varphi_1$$

$$\Rightarrow K_{S_1} = K_{S_2} \circ f \quad \checkmark$$