H^2 REGULARITY FOR THE $p(x)$ –LAPLACIAN IN TWO-DIMENSIONAL CONVEX DOMAINS

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ABSTRACT. In this paper we study the H^2 global regularity for solutions of the $p(x)$ –Laplacian in two dimensional convex domains with Dirichlet boundary conditions. Here $p : \Omega \to [p_1, \infty)$ with $p \in \text{Lip}(\overline{\Omega})$ and $p_1 > 1$.

1. INTRODUCTION

Let Ω be a bounded domain in \mathbb{R}^2 and let $p : \Omega \to (1, +\infty)$ be a measurable function. In this work, we study the H^2 global regularity of the weak solution of the following problem

(1.1)
$$
\begin{cases} -\Delta_{p(x)}u = f & \text{in } \Omega, \\ u = g & \text{on } \partial\Omega, \end{cases}
$$

where $\Delta_{p(x)} u = \text{div}(|\nabla u|^{p(x)-2} \nabla u)$ is the $p(x)$ -Laplacian. The hypothesis over p , f and g will be specified later.

Note that, the $p(x)$ –Laplacian extends the classical Laplacian $(p(x) \equiv 2)$ and the p–Laplacian $(p(x) \equiv p$ with $1 < p < +\infty$). This operator has been recently used in image processing and in the modeling of electrorheological fluids, see [3, 5, 24].

Motivate by the applications to image processing problem, in [8], the authors study two numerical methods to approximate solutions of the type of (1.1). In Theorem 5.1, the authors prove the convergence in $W^{1,p(\cdot)}(\Omega)$ of the conformal Galerking finite element method. It is of our interest to study, in a future work, the rate of this convergence. In general, all the error bounds depend on the global regularity of the second derivatives of the solutions, see for example [6, 22]. However, there appear to be no existing regularity results in the literature that can be applied here, since all the results have either a first order or local character.

The H^2 global regularity for solutions of the p-Laplacian is studied in [22]. There the authors prove the following: Let $1 < p \leq 2$, $g \in H^2(\Omega)$, $f \in L^{q}(\Omega)$ $(q > 2)$ and u be the unique weak solution of (1.1). Then

- If $\partial\Omega \in C^2$ then $u \in H^2(\Omega)$;
- If Ω is convex and $g = 0$ then $u \in H^2(\Omega)$;

Key words and phrases. Variable exponent spaces. Elliptic Equations. H^2 regularity. 2010 Mathematics Subject Classification. 35B65, 35J60, 35J70.

Supported by UBA X117, UBA 20020090300113, CONICET PIP 2009 845/10 and PIP 11220090100625.

• If Ω is convex with a polygonal boundary and $g \equiv 0$ then $u \in C^{1,\alpha}(\overline{\Omega})$ for some $\alpha \in (0,1)$.

Regarding the regularity of the weak solution of (1.1) when $f = 0$, in [1, 7], the authors prove the $C_{loc}^{1,\alpha}$ regularity (in the scalar case and also in the vectorial case). Then, in the paper [15] the authors study the case where the functional has the so called (p, q) growth conditions. Following these ideas, in [17], the author proves that the solutions of (1.1) are in $C^{1,\alpha}(\overline{\Omega})$ for some $\alpha > 0$ if Ω is a bounded domain in \mathbb{R}^N $(N \geq 2)$ with $C^{1,\gamma}$ boundary, $p(x)$ is a Hölder function, $f \in L^{\infty}(\Omega)$ and $g \in C^{1,\gamma}(\overline{\Omega})$. While in [4], the authors prove that the solutions are in $H^2_{loc}(\{x \in \Omega : p(x) \le 2\})$ if $p(x)$ is uniformly Lipschitz $(\text{Lip}(\Omega))$ and $f \in W_{loc}^{1,q(\cdot)}(\Omega) \cap L^{\infty}(\Omega)$.

Our aim, it is to generalized the results of [22] in the case where $p(x)$ is a measurable function. To this end, we will need some hypothesis over the regularity of $p(x)$. Moreover, in all our result we can avoid the restriction $q = 0$, assuming some regularity of $q(x)$.

On the other hand, to prove our results, we can assume weaker conditions over the function f than the ones on [4]. Since, we only assume that $f \in$ $L^{q(\cdot)}(\Omega)$, we do not have a priori that the solutions are in $C^{1,\alpha}(\Omega)$. Then we can not use it to prove the H^2 global regularity. Nevertheless, we can prove that the solutions are in $C^{1,\alpha}(\overline{\Omega})$, after proving the H^2 global regularity.

The main results of this paper are:

Theorem 1.1. Let Ω be a bounded domain in \mathbb{R}^2 with C^2 boundary, $p \in \mathbb{R}$ $\text{Lip}(\overline{\Omega})$ with $p(x) \geq p_1 > 1$, $g \in H^2(\Omega)$ and u be the weak solution of (1.1). If

(F1) $f \in L^{q(x)}(\Omega)$ with $q(x) \ge q_1 > 2$ in the set $\{x \in \Omega : p(x) \le 2\};$

(F2) $f \equiv 0$ in the set $\{x \in \Omega : p(x) > 2\}.$

then $u \in H^2(\Omega)$.

Theorem 1.2. Let Ω be a bounded domain in \mathbb{R}^2 with convex boundary, $p \in \text{Lip}(\overline{\Omega})$ with $p(x) \geq p_1 > 1$, $g \in H^2(\Omega)$ and u be the weak solution of (1.1). If f satisfies (F1) and (F2) then $u \in H^2(\Omega)$.

Using the above theorem we can prove the following,

Corollary 1.3. Let Ω be a bounded convex domain in \mathbb{R}^2 with polygonal boundary, p and f as in the previous theorem, $g \in W^{2,q(x)}(\Omega)$ and u be the weak solution of (1.1) then $u \in C^{1,\alpha}(\overline{\Omega})$ for some $0 < \alpha < 1$.

Observe that this result extends the one in [17] in the case where Ω is a polygonal domain in \mathbb{R}^2 .

Organization of the paper. The rest of the paper is organized as follows. After a short Section 2 where we collect some preliminaries results, in Section 3, we study the H^2 – regularity for the non-degenerated problem. In Section 4 we prove Theorem 1.1. Then, in Section 5, we study the regularity of the solution u of (1.1) if Ω is convex. In Section 6, we make some comments on the dependence of the H^2 –norm of u on p_1 . Lastly, in Appendices A

and B we give some results related to elliptic linear equation with bounded coefficients and Lipschitz functions, respectively.

2. Preliminaries

We now introduce the space $L^{p(\cdot)}(\Omega)$ and $W^{1,p(\cdot)}(\Omega)$ and state some of their properties.

Let Ω be a bounded open set of \mathbb{R}^n and $p: \Omega \to [1, +\infty)$ be a measurable bounded function, called a variable exponent on Ω and denote $p_1 := e \sin f p(x)$ and $p_2 := e \sin p(x)$.

We define the variable exponent Lebesgue space $L^{p(\cdot)}(\Omega)$ to consist of all measurable functions $u: \Omega \to \mathbb{R}$ for which the modular

$$
\varrho_{p(\cdot)}(u) := \int_{\Omega} |u(x)|^{p(x)} dx
$$

is finite. We define the Luxemburg norm on this space by

$$
||u||_{L^{p(\cdot)}(\Omega)} := \inf\{k > 0 \colon \varrho_{p(\cdot)}(u/k) \le 1\}.
$$

This norm makes $L^{p(\cdot)}(\Omega)$ a Banach space.

For the proofs of the following theorems, we refer the reader to [12].

Theorem 2.1 (Hölder's inequality). Let $p, q, s : \Omega \to [1, +\infty]$ be a measurable functions such that

$$
\frac{1}{p(x)} + \frac{1}{q(x)} = \frac{1}{s(x)} \quad \text{in } \Omega.
$$

Then the inequality

$$
||fg||_{L^{s(\cdot)}(\Omega)} \leq 2||f||_{L^{p(\cdot)}(\Omega)}||g||_{L^{q(\cdot)}(\Omega)}
$$

for all $f \in L^{p(\cdot)}(\Omega)$ and $g \in L^{q(\cdot)}(\Omega)$

Let $W^{1,p(\cdot)}(\Omega)$ denote the space of measurable functions u such that, u and the distributional derivative ∇u are in $L^{p(\cdot)}(\Omega)$. The norm

$$
||u||_{W^{1,p(\cdot)}(\Omega)} := ||u||_{p(\cdot)} + |||\nabla u|||_{p(\cdot)}
$$

makes $W^{1,p(\cdot)}(\Omega)$ a Banach space.

Theorem 2.2. Let $p'(x)$ such that, $1/p(x) + 1/p'(x) = 1$. Then $L^{p'(\cdot)}(\Omega)$ is the dual of $L^{p(\cdot)}(\Omega)$. Moreover, if $p_1 > 1$, $L^{p(\cdot)}(\Omega)$ and $W^{1,p(\cdot)}(\Omega)$ are reflexive.

We define the space $W_0^{1,p(\cdot)}$ $O_0^{(1,p(\cdot))}(\Omega)$ as the closure of the $C_0^{\infty}(\Omega)$ in $W^{1,p(\cdot)}(\Omega)$. Then we have the following version of Poincare's inequity (see Theorem 3.10 in [21]).

Lemma 2.3 (Poincare's inequity). If $p : \Omega \to [1, +\infty)$ is continuous in $\overline{\Omega}$, there exists a constant C such that for every $u \in W_0^{1,p(\cdot)}$ $\mathcal{O}^{(1,p(\cdot))}(\Omega),$

$$
||u||_{L^{p(\cdot)}(\Omega)} \leq C||\nabla u||_{L^{p(\cdot)}(\Omega)}.
$$

In order to have better properties of these spaces, we need more hypotheses on the regularity of $p(x)$.

We say that p is log-Hölder continuous in Ω if there exists a constant C_{loop} such that

$$
|p(x) - p(y)| \le \frac{C_{log}}{\log\left(e + \frac{1}{|x-y|}\right)} \quad \forall x, y \in \Omega.
$$

It was proved in [10], Theorem 3.7, that if one assumes that p is log-Hölder continuous then $C^{\infty}(\overline{\Omega})$ is dense in $W^{1,p(\cdot)}(\Omega)$ (see also [9, 12, 13, 21, 25]).

We now state the Sobolev embedding Theorem (for the proofs see [12]). Let,

$$
p^*(x) := \begin{cases} \frac{p(x)N}{N - p(x)} & \text{if } p(x) < N, \\ +\infty & \text{if } p(x) \ge N, \end{cases}
$$

be the Sobolev critical exponent. Then we have the following,

Theorem 2.4. Let Ω be a Lipschitz domain. Let $p : \Omega \to [1,\infty)$ and p log-Hölder continuous. Then the imbedding $W^{1,p(\cdot)}(\Omega) \hookrightarrow L^{p^*(\cdot)}(\Omega)$ is continuous.

3. H^2 –REGULARITY FOR THE NON-DEGENERATED PROBLEM FOR ANY dimension

In this section we assume that Ω is a bounded domain in \mathbb{R}^N , with $N \geq 2$.

We want to study higher regularity of the weak solution of the regularized equation,

(3.2)
$$
\begin{cases} -\operatorname{div}\left((\varepsilon + |\nabla u|^2)^{\frac{p(x)-2}{2}} \nabla u \right) = f & \text{in } \Omega, \\ u = g & \text{on } \partial \Omega, \end{cases}
$$

where $0 < \varepsilon \leq 1$, and $f \in \text{Lip}(\Omega)$ and $g \in W^{1,p(\cdot)}(\Omega)$.

The existence of a weak solution of (3.2) holds by Theorem 13.3.3 in [12].

Remark 3.1. Given $\varepsilon \geq 0$, $p \in C^{\alpha_0}(\overline{\Omega})$ for some $\alpha_0 > 0$, and $g \in L^{\infty}(\Omega)$ we have the following results,

- (1) Since $f, g \in L^{\infty}(\Omega)$, by Theorem 4.1 in [18], we have that $u \in L^{\infty}(\Omega)$.
- (2) By Theorem 1.1 in [17], $u \in C_{loc}^{1,\alpha}(\Omega)$ for some α depending on p_1, p_2 , $||u||_{L^{\infty}(\Omega)}, ||f||_{L^{\infty}(\Omega)}$. Moreover, given $\Omega_0 \subset\subset \Omega$, $||u||_{C^{1,\alpha}(\Omega_0)}$ depends on the same constants and $dist(\Omega_0, \partial \Omega)$.
- (3) Finally, by Theorem 1.2 in [17], if $\partial \Omega \in C^{1,\gamma}$ and $g \in C^{1,\gamma}(\partial \Omega)$ for some $\gamma > 0$ then $u \in C^{1,\alpha}(\overline{\Omega})$, where α and $||u||_{C^{1,\alpha}(\Omega)}$ depend on $p_1, p_2, N, ||u||_{L^{\infty}(\Omega)}, ||p||_{C^{\alpha_0}(\Omega)}, \alpha_0, \gamma.$

We will first prove the H^2 -local regularity assuming only that $p(x)$ is Lipschitz. Then, we will prove the global regularity under the stronger condition that $\nabla p(x)$ is Hölder.

3.1. H^2 –**Local regularity.** While we where finishing this paper, we found the work [4], where the authors give a different proof of the H^2 -local regularity of the solutions of (3.2). Anyhow, we leave the proof for the completeness of this paper.

Theorem 3.2. Let $p, f \in \text{Lip}(\Omega)$ with $p_1 > 1$ and u a weak solution of (3.2), then $u \in H_{loc}^2(\Omega)$.

Proof. First, let us define for any function F and $h > 0$,

$$
\Delta^h F(x) = \frac{F(x + \mathbf{h}) - F(x)}{h},
$$

where $\mathbf{h} = h e_k$ where e_k is a vector of the canonical base of \mathbb{R}^N .

Let $\eta(x) = \xi(x)^2 \Delta^h u(x)$ where ξ is a regular function with compact support. Therefore, if we take $v_{\varepsilon} = (|\nabla u|^2 + \varepsilon)^{1/2}$ and $h < \text{dist}(\text{supp}(\xi), \partial \Omega)$, we have

$$
\int_{\Omega} \langle v_{\varepsilon}(x)^{p(x)-2} \nabla u(x), \nabla \eta(x) \rangle dx = \int_{\Omega} f(x) \eta(x) dx
$$

$$
\int_{\Omega} \langle v_{\varepsilon}(x+\mathbf{h})^{p(x+\mathbf{h})-2} \nabla u(x+\mathbf{h}), \nabla \eta(x) \rangle dx = \int_{\Omega} f(x+\mathbf{h}) \eta(x) dx.
$$

Subtracting, using that $\nabla \eta = 2 \xi \nabla \xi \Delta^h u + \xi^2 \Delta^h (\nabla u)$ and dividing by h we obtain,

$$
I = \int_{\Omega} \langle \Delta^h (v_{\varepsilon}(x)^{p(x)-2} \nabla u), \Delta^h (\nabla u) \rangle \xi^2 dx
$$

= $- 2 \int_{\Omega} \langle \Delta^h (v_{\varepsilon}(x)^{p(x)-2} \nabla u), \xi \nabla \xi \Delta^h u \rangle dx + \int_{\Omega} \xi^2 \Delta^h f \Delta^h u dx$
= $2 \int_{\Omega} \left(\int_0^1 (v_{\varepsilon}(x + \mathbf{h} t)^{p(x + \mathbf{h} t) - 2} \nabla u(x + \mathbf{h} t) dt) \right) \frac{\partial}{\partial x_k} (\xi \nabla \xi \Delta^h u) dx$
+ $\int_{\Omega} \xi^2 \Delta^h f \Delta^h u dx$
= $I I + II I$.

Now, let as fix a ball B_R such that $B_{3R} \subset\subset \Omega$ and take $\xi \in C_0^{\infty}(\Omega)$ supported in B_{2R} such that $0 \leq \xi \leq 1$, $\xi = 1$ in B_R , $|\nabla \xi| \leq 1/R$ and $|D^2\xi| \leq CR^{-2}$.

By Remark 3.1, there exist a constant $C_1 > 0$ such that $|\nabla u| \leq C_1$ in B_{3R} , therefore we get

$$
II \le 2 \int_{B_{2R}} \frac{C}{R} |\Delta^h u_{x_k}| \xi \, dx + 2 \int_{B_{2R}} \frac{C}{R^2} |\Delta^h u| \, dx
$$

$$
\le \frac{C}{R} \int_{B_{2R}} |\Delta^h (\nabla u)| \xi \, dx + CR^{N-2}.
$$

On the other hand, since f is Lipschitz we have that,

$$
|f(x + \mathbf{h}) - f(x)| \le C_2 h
$$

for some constant $C_2 > 0$. This implies that,

$$
III \leq C_2 R^N.
$$

Therefore, summing II and III, and using Young's inequality, we have that for any $\delta > 0$

(3.3)
$$
I \leq \delta \int_{B_{2R}} |\Delta^h(\nabla u)|^2 \xi^2 dx + C,
$$

for some constant C depending on R and δ .

On the other hand observe that $I = I_1 + I_2$ where,

$$
I_1 = \frac{1}{h} \int_{B_{2R}} \langle (v_{\varepsilon}(x+\mathbf{h})^{p(x+\mathbf{h})-2} \nabla u(x+\mathbf{h}) - v_{\varepsilon}(x)^{p(x+\mathbf{h})-2} \nabla u(x)), \Delta^h(\nabla u) \rangle \xi^2 dx,
$$

and

$$
I_2 = \frac{1}{h} \int_{B_{2R}} \langle \left(v_{\varepsilon}(x)^{p(x+h)} - v_{\varepsilon}(x)^{p(x)} \right) \frac{\nabla u(x)}{v_{\varepsilon}(x)^2}, \Delta^h(\nabla u) \rangle \xi^2 dx.
$$

Using that $p(x)$ is Lipschitz and the fact that $|\nabla u(x)| \leq C_1$ we have that, for some b between $p(x+h)$ and $p(x)$,

$$
\frac{1}{h}\left|v_{\varepsilon}(x)^{p(x+\mathbf{h})}-v_{\varepsilon}(x)^{p(x)}\right|=\left|v_{\varepsilon}(x)^{b}\log(v_{\varepsilon}(x))\frac{p(x+\mathbf{h})-p(x)}{h}\right|\leq C,
$$

for some constant $C > 0$ depending on $p_1, p_2, \varepsilon, C_1$ and the Lipschitz constant of $p(x)$.

Therefore, we have that

$$
-I_2 \leq CC_1 \varepsilon^{-1} \int_{B_{2R}} |\Delta^h(\nabla u)| \xi^2 dx.
$$

By (3.3), the last inequality and using again Young's inequality we have that, for any $\delta > 0$

(3.4)
$$
I_1 \leq \delta \int_{B_{2R}} |\Delta^h(\nabla u)|^2 \xi^2 dx + C,
$$

for some constant $C > 0$ depending on $p_1, p_2, \varepsilon, C_1$ and the Lipschitz constant of $p(x)$.

To finish the proof, we have to find a lower bound for I_1 . By a well known inequality, we have that

$$
\langle (v_{\varepsilon}(x+\mathbf{h})^{p(x+h)-2} \nabla u(x+\mathbf{h}) - v_{\varepsilon}(x)^{p(x+\mathbf{h})-2} \nabla u(x)), (\nabla u(x+\mathbf{h}) - \nabla u(x)) \rangle
$$

\n
$$
\geq C_{\varepsilon} |\nabla u(x+\mathbf{h}) - \nabla u(x)|^2,
$$

where

$$
C_{\varepsilon} = \begin{cases} \varepsilon^{p(x+\mathbf{h})-2/2} & \text{if } p(x+\mathbf{h}) \ge 2, \\ (p(x+\mathbf{h})-1)\varepsilon^{p(x+\mathbf{h})-2/2} & \text{if } p(x+\mathbf{h}) \le 2. \end{cases}
$$

Therefore, using that $p_1 > 1$, we arrive at

$$
I_1 \ge \int_{B_{2R}} Ch^{-2} |\nabla u(x+\mathbf{h}) - \nabla u(x)|^2 \xi^2 dx = C \int_{B_{2R}} |\Delta^h(\nabla u(x))|^2 \xi^2 dx.
$$

Finally combining the last inequality with (3.4) we have that,

$$
\int_{B_R} |\Delta^h(\nabla u(x))|^2 dx \le C(N, p, f, \varepsilon).
$$

This proves that $u \in H^2_{loc}(\Omega)$.

$$
\sqcup
$$

3.2. H^2 –Global Regularity. Now we want to prove that if $f \in \text{Lip}(\Omega)$ and $g \in C^{1,\beta}(\partial\Omega)$, the regularized equation (3.2) has a weak solution $u \in$ $C^2(\Omega) \cap C^{1,\alpha}(\overline{\Omega})$ for an $\alpha \in (0,1)$. We already know, by Remark 3.1, that $u \in C^{1,\alpha}(\overline{\Omega})$. Then, we only need to prove that $u \in C^2(\Omega)$.

Lemma 3.3. Let Ω be a bounded domain in \mathbb{R}^N with $\partial\Omega \in C^{1,\gamma}$, $p \in$ $C^{1,\beta}(\Omega) \cap C^{\alpha_0}(\overline{\Omega}),$ $f \in \text{Lip}(\Omega)$ and $g \in C^{1,\beta}(\partial \Omega)$. Then, the Dirichlet Problem (3.2) has a solution $u \in C^2(\Omega) \cap C^{1,\alpha}(\overline{\Omega})$.

Proof. Observe that by Theorem 3.2, we know that the solution is in $H_{loc}^2(\Omega)$. Then for any $\Omega' \subset\subset \Omega$ we can derive the equation and look the solution of (3.2) as the solution of the following equation,

(3.5)
$$
\begin{cases} L_{\varepsilon}u = a(x) & \text{in } \Omega', \\ u = u & \text{on } \partial\Omega'. \end{cases}
$$

Here,

$$
L_{\varepsilon}u = a_{ij}^{\varepsilon}(x)u_{x_ix_j}
$$

with

(3.6)
$$
a_{ij}^{\varepsilon}(x) = \delta_{ij} + (p(x) - 2) \frac{u_{x_i} u_{x_j}}{v_{\varepsilon}^2}, \quad v_{\varepsilon} = (\varepsilon + |\nabla u|^2)^{\frac{1}{2}},
$$

$$
a_{\varepsilon}(x) = \ln(v_{\varepsilon}) \langle \nabla u, \nabla p \rangle + f v_{\varepsilon}^{2-p}.
$$

The operator L_{ε} is uniformly elliptic in Ω , since for any $\xi \in \mathbb{R}^N$

$$
(3.7) \qquad \min\{(p_1-1),1\}|\xi|^2 \le a_{ij}^{\varepsilon}\xi_i\xi_j \le \max\{(p_2-1),1\}|\xi|^2.
$$

On the other hand, by Remark 3.1, $u \in C^{1,\alpha}(\overline{\Omega})$. Then, $a_{ij}^{\varepsilon} \in C^{\alpha}(\overline{\Omega})$, since $\varepsilon > 0$. Using that $f \in \text{Lip}(\Omega)$, we have that $a \in C^{\rho}(\Omega)$ where $\rho = \min(\alpha, \beta)$. If $\partial \Omega' \in C^2$, as u is the unique solution of (3.5), by Theorem 6.13 in [19], we have that $u \in C^{2,\rho}(\Omega')$. This ends the proof.

 \Box

Remark 3.4. By the H^2 global estimate for linear elliptic equations with $L^{\infty}(\Omega)$ coefficients in two variables (see Lemma A.1 and (3.7)) we have that,

$$
||u||_{H^2(\Omega)} \leq C \left(||a_{\varepsilon}||_{L^2(\Omega)} + ||g||_{H^2(\Omega)} \right)
$$

where u is the solution of (3.2) and C is a constant independents of ε .

4. Proof of Theorem 1.1

Before proving the theorem, we will need a global bound for the derivatives of the solutions of (3.2).

Lemma 4.1. Let $f \in L^{q(x)}(\Omega)$ with $q'(x) \leq p^*(x)$, $g \in W^{1,p(\cdot)}(\Omega)$, $\varepsilon > 0$ and u_{ε} be the weak solution of (3.2) then

$$
\|\nabla u_{\varepsilon}\|_{L^{p(\cdot)}(\Omega)} \leq C
$$

where C is a constant depending on $||f||_{L^q(\cdot)(\Omega)}, ||g||_{W^{1,p(\cdot)}(\Omega)}$ but not on ε .

Proof. Let

$$
J(v) := \int_{\Omega} \frac{1}{p(x)} (|\nabla v|^2 + \varepsilon)^{p(x)/2} dx.
$$

By the convexity of J and using (3.2) we have that,

$$
J(u_{\varepsilon}) \leq J(g) - \int_{\Omega} (|\nabla u_{\varepsilon}|^{2} + \varepsilon)^{(p-2)/2} \nabla u_{\varepsilon} (\nabla g - \nabla u_{\varepsilon}) dx
$$

\n
$$
\leq C \left(1 + \int_{\Omega} f(u_{\varepsilon} - g) dx \right)
$$

\n
$$
\leq C \left(1 + ||f||_{L^{q(\cdot)}(\Omega)} ||u_{\varepsilon} - g||_{L^{q'(\cdot)}(\Omega)} \right)
$$

\n
$$
\leq C \left(1 + ||f||_{L^{q(\cdot)}(\Omega)} ||\nabla u_{\varepsilon} - \nabla g||_{L^{p(\cdot)}(\Omega)} \right),
$$

where in the last inequality we are using that $W^{1,p(\cdot)}(\Omega) \hookrightarrow L^{p^*(\cdot)}(\Omega)$ continuously and Poincare's inequality.

Thus we have that there exist a constant independent of ε such that,

$$
\int_{\Omega} |\nabla u_{\varepsilon}|^{p(x)} dx \leq C(1 + ||\nabla u_{\varepsilon}||_{L^{p(\cdot)}(\Omega)}),
$$

and using the properties of the $L^{p(\cdot)}(\Omega)$ – norms this means that

$$
\|\nabla u_{\varepsilon}\|_{L^{p(\cdot)}(\Omega)}^m \leq C(1+\|\nabla u_{\varepsilon}\|_{L^{p(\cdot)}(\Omega)}),
$$

for some $m > 1$. Therefore $\|\nabla u_{\varepsilon}\|_{L^{p(\cdot)}(\Omega)}$ is bounded independent of ε . \square

To prove Theorem 1.1, we will use the results of Section 3. Therefore, we will first need to assume that $p \in C^{1,\beta}(\Omega) \cap C(\overline{\Omega})$.

Theorem 4.2. Let Ω be a bounded domain in \mathbb{R}^2 with C^2 boundary, $p \in \mathbb{R}$ $C^{1,\beta}(\Omega) \cap C^{\alpha_0}(\overline{\Omega})$ with $p(x) \geq p_1 > 1$, $g \in H^2(\Omega)$ and u be the weak solution of (1.1). If f satisfies (F1) and (F2) then $u \in H^2(\Omega)$.

Proof. Let $f_{\varepsilon} \in \text{Lip}(\Omega)$ and $g_{\varepsilon} \in C^{2,\alpha}(\overline{\Omega})$ such that

$$
f_{\varepsilon} \to f
$$
 strongly in $L^{q(\cdot)}(\Omega)$,

 $g_{\varepsilon} \to g$ strongly in $H^2(\Omega)$,

as $\varepsilon \to 0$. Observe that, since $f(x) = 0$ if $p(x) > 2$, we can take $f_{\varepsilon} \equiv 0$ in $\{x \in \Omega : p(x) > 2\}.$

Now, let us consider the solution of (3.2) as the solution of

$$
\begin{cases} a_{11}^{\varepsilon}(x)\frac{\partial^2 u_{\varepsilon}}{\partial x_1^2} + 2a_{12}^{\varepsilon}(x)\frac{\partial^2 u_{\varepsilon}}{\partial x_1 \partial x_2} + a_{22}^{\varepsilon}(x)\frac{\partial^2 u_{\varepsilon}}{\partial x_2^2} = a_{\varepsilon}(x) & \text{in } \Omega, \\ u_{\varepsilon} = g_{\varepsilon} & \text{on } \partial\Omega, \end{cases}
$$

where $a_{11}^{\varepsilon}, a_{22}^{\varepsilon}, a_{12}^{\varepsilon}$, are defined as in Lemma 3.3, substituting f and g by f_{ε} and g_{ε} respectively. By Lemma 3.3 we know that $u_{\varepsilon} \in C^2(\Omega) \cap C^{1,\alpha}(\overline{\Omega})$.

First we will prove the ${u_{\varepsilon}}_{\varepsilon\in(0,1]}$ is bounded in $H^2(\Omega)$. By Remark 3.4, we have that

$$
(4.8) \quad \|u_{\varepsilon}\|_{H^{2}(\Omega)} \leq C(\|a_{\varepsilon}(x)\|_{L^{2}(\Omega)} + \|g_{\varepsilon}\|_{H^{2}(\Omega)})
$$

$$
\leq C(\|\ln(v_{\varepsilon})\nabla u_{\varepsilon}\nabla p\|_{L^{2}(\Omega)} + \|f_{\varepsilon}v^{2-p}\|_{L^{2}(\Omega)} + \|g_{\varepsilon}\|_{H^{2}(\Omega)}).
$$

Taking $\Omega_1 = \{x \in \Omega : |\nabla u_\varepsilon(x)| > 1\}$, using that $p(x)$ is Lipschitz and Hölder's inequality, we have

$$
(4.9) \quad \|\ln(v_{\varepsilon})\nabla u_{\varepsilon}\nabla p\|_{L^{2}(\Omega)} \leq C \|\ln^{2}(v_{\varepsilon})\nabla u_{\varepsilon}\|_{L^{p'(\cdot)}(\Omega_{1})}^{1/2} \|\nabla u_{\varepsilon}\|_{L^{p(\cdot)}(\Omega_{1})}^{1/2} + C.
$$

On the other hand, since $q(x) \ge q_1 > 2$, we have that $q'(x) \le p^*(x)$. Then, as $||f_{\varepsilon}||_{L^{q(\cdot)}(\Omega)}$ and $||g_{\varepsilon}||_{H^{2}(\Omega)}$ are bounded independent of ε , using Lemma 4.1 we conclude that $\|\nabla u_{\varepsilon}\|_{L^{p(\cdot)}(\Omega)}$ is uniformly bounded.

Observe that, for all $s > 0$ there exist a constant $C > 0$ such that

$$
\ln(v_{\varepsilon}) \le C v_{\varepsilon}^{s/2} < C |\nabla u_{\varepsilon}|^{s/2} \quad \text{in } \Omega_1,
$$

thus

$$
\begin{aligned} \|\ln^2(v_{\varepsilon})|\nabla u_{\varepsilon}\|\|_{L^{p'(\cdot)}(\Omega_1)} &\leq C\||\nabla u_{\varepsilon}|^{1+s}\|_{L^{p'(\cdot)}(\Omega_1)}\\ &\leq C\|\nabla u_{\varepsilon}\|_{L^{p'(\cdot)(1+s)}(\Omega_1)}^{(1+s)}\\ &\leq C\|u_{\varepsilon}\|_{H^2(\Omega_1)}^{(1+s)}.\end{aligned}
$$

In the last line, we are using that $2^* = \infty$, since $N = 2$.

Then, by the last inequality, (4.8) and (4.9) , we get

$$
(4.10) \t\t\t ||u_{\varepsilon}||_{H^{2}(\Omega)} \leq C \left(||u_{\varepsilon}||_{H^{2}(\Omega)}^{(1+s)/2} + ||f_{\varepsilon}v_{\varepsilon}^{2-p}||_{L^{2}(\Omega)} + 1 \right).
$$

Taking

$$
A_1 = \{x \in \Omega : p(x) = 2\} \text{ and } A_2 = \{x \in \Omega : p(x) < 2\}
$$

and using that $f_{\varepsilon} \equiv 0$ in $\{x \in \Omega : p(x) > 2\}$, we have that

$$
||f_{\varepsilon}v_{\varepsilon}^{2-p}||_{L^{2}(\Omega)} \leq ||f_{\varepsilon}||_{L^{2}(A_{1})} + ||f_{\varepsilon}v_{\varepsilon}^{2-p}||_{L^{2}(A_{2})}.
$$

Since $||f_{\varepsilon}||_{L^2(A_1)}$ is bounded, to prove that ${u_{\varepsilon}}_{\varepsilon\in(0,1]}$ is bounded in $H^2(\Omega)$, we only have to find a bound of $||f_{\varepsilon}v_{\varepsilon}^{2-p}||_{L^{2}(A_2)}$.

Let as define in A_2 the function

$$
\widetilde{q}(x) = \begin{cases} \frac{1}{2p(x)-3} + 1 & \text{if } \frac{1}{q(x)} + \frac{3}{2} \le p(x) < 2, \\ \frac{q(x)}{2} + 1 & \text{if } p(x) < \frac{1}{q(x)} + \frac{3}{2}. \end{cases}
$$

It is easy to see that $2 < \widetilde{q}(x) \leq q(x)$ for any $x \in A_2$.

On the other hand, let us denote $\mu(x) = \frac{2\tilde{q}(x)}{\tilde{q}(x)-x}$ $\frac{2q(x)}{\widetilde{q}(x)-2}$ and $\gamma(x) = \mu(x)(2-p(x))$ then

$$
1 < 1 + \frac{2}{q_2} \le \gamma(x) \le \max\left\{2, 2 + \frac{8}{q_1 - 2}\right\} \quad \forall x \in A_2.
$$

Now, using Hölder's inequality with exponent $\tilde{q}(x)/2$, we have

(4.11)
$$
\|f_{\varepsilon}v_{\varepsilon}^{2-p}\|_{L^{2}(A_2)} \leq C \|f_{\varepsilon}\|_{L^{\widetilde{q}(\cdot)}(A_2)} \|v_{\varepsilon}^{2-p}\|_{L^{\mu(\cdot)}(A_2)}.
$$

Then, if $||v_{\varepsilon}||_{L^{\gamma(\cdot)}(A_2)} \leq 1$ we have $||v_{\varepsilon}^{2-p}||_{L^{\mu(\cdot)}(A_2)} \leq 1$ and since $\widetilde{q}(x) \leq$ $q(x)$ we get

$$
||f_{\varepsilon}v_{\varepsilon}^{2-p}||_{L^{2}(A_{2})} \leq C.
$$

If $||v||_{L^{\gamma(\cdot)}(A_2)} \geq 1$, we have

$$
(4.12) \t\t\t ||v_{\varepsilon}^{2-p}||_{L^{\mu(\cdot)}(A_2)} \leq ||v_{\varepsilon}||_{L^{\gamma(\cdot)}(A_2)}^{2-p_1} \leq C(1+||\nabla u_{\varepsilon}||_{L^{\gamma(\cdot)}(A_2)}^{2-p_1}),
$$

where in the last inequality we are using that $\varepsilon \leq 1$.

Since $2^* = \infty$ and $1 < \gamma_1 \leq \gamma(x) \leq \gamma_2 < \infty$, by the Sobolev embedding inequality, we have that

$$
\|\nabla u_{\varepsilon}\|_{L^{\gamma(\cdot)}(A_2)}^{2-p_1} \leq C \|u_{\varepsilon}\|_{H^2(A_2)}^{2-p_1} \leq C \|u_{\varepsilon}\|_{H^2(\Omega)}^{2-p_1}.
$$

Combining this last inequality with inequalities (4.12) , (4.11) , (4.10) and the fact that $\tilde{q}(x) \leq q(x)$, we get

$$
||u_{\varepsilon}||_{H^{2}(\Omega)} \leq C(||u_{\varepsilon}||_{H^{2}(\Omega)}^{(1+s)/2} + ||u_{\varepsilon}||_{H^{2}(\Omega)}^{2-p_{1}} + 1).
$$

Finally, we get that for any $0 < s < 1$ there exist a constant $C =$ $C(p, q, f, s)$ such that

$$
||u_{\varepsilon}||_{H^2(\Omega)} \leq C.
$$

Then, there exist a subsequence still denoted $\{u_{\varepsilon}\}_{{\varepsilon \in (0,1]}}$ and $u \in H^1(\Omega)$ such that

$$
u_{\varepsilon} \to u
$$
 strongly in $H^1(\Omega)$,
 $u_{\varepsilon} \to u$ weakly in $H^2(\Omega)$,

It is clear that u satisfies the boundary condition.

Lastly, by Proposition 3.2 in [2], there exist a constant $M > 0$ independent of ε such that,

$$
(4.13)\ \ |(\varepsilon+|\nabla u_{\varepsilon}|^2)^{\frac{p(x)-2}{2}}\nabla u_{\varepsilon}-(\varepsilon+|\nabla u|^2)^{\frac{p(x)-2}{2}}\nabla u|\leq M|\nabla(u_{\varepsilon}-u)|^{p(x)-1}
$$

for all $x \in \Omega$. Then, passing to the limit in the weak formulation of (3.2) and using the above inequality, we have that

$$
\int_{\Omega} |\nabla u|^{p(x)-2} \nabla u \nabla \varphi \, dx = \int_{\Omega} f \varphi \, dx
$$

for any $\varphi \in C_0^{\infty}(\Omega)$. Therefore $u \in H^2(\Omega)$ and solves (1.1).

Now, we are able to prove the theorem.

Proof of Theorem 1.1. First, we consider the case $p \in C^1(\overline{\Omega})$. Let $p_{\varepsilon} \in C^1(\overline{\Omega})$. $C^{\infty}(\overline{\Omega})$ such that $p_{\varepsilon} \to p$ in $C^1(\Omega)$. Now, we define

(4.14)
$$
f_{\varepsilon}(x) = \begin{cases} f(x) & \text{if } p_{\varepsilon}(x) \leq 2, \\ 0 & \text{if } p_{\varepsilon}(x) > 2. \end{cases}
$$

Observe that $f_{\varepsilon} \to f$ in $L^{q(\cdot)}(\Omega)$ as $\varepsilon \to 0$.

Then, by Theorem 4.2, the solution u_{ε} of (1.1) (with p_{ε} and f_{ε} instead of p and f) is bounded in $H^2(\Omega)$ by a constant independent of ε . Therefore, there exist a subsequence still denoted $\{u_{\varepsilon}\}_{{\varepsilon} \in (0,1]}$ and $u \in H^2(\Omega)$ such that

(4.15)
$$
u_{\varepsilon} \to u \quad \text{in } H^{1}(\Omega),
$$

$$
u_{\varepsilon} \to u \quad \text{weakly in } H^{2}(\Omega).
$$

H^2 REGULARITY FOR THE $p(x)$ −LAPLACIAN IN TWO-DIMENSIONAL 11

It remains to prove that u is a solution of (1.1). Let $\varphi \in C_0^{\infty}(\Omega)$, then

(4.16)
\n
$$
\int_{\Omega} f_{\varepsilon} \varphi \, dx = \int_{\Omega} |\nabla u_{\varepsilon}|^{p_{\varepsilon}(x)-2} \nabla u_{\varepsilon} \nabla \varphi \, dx
$$
\n
$$
= \int_{\Omega} |\nabla u_{\varepsilon}|^{p(x)-2} \nabla u_{\varepsilon} \nabla \varphi \, dx
$$
\n
$$
+ \int_{\Omega} (|\nabla u_{\varepsilon}|^{p_{\varepsilon}(x)-2} - |\nabla u_{\varepsilon}|^{p(x)-2}) \nabla u_{\varepsilon} \nabla \varphi \, dx.
$$

Therefore, using that $H^2(\Omega) \hookrightarrow W^{1,p(\cdot)}(\Omega)$ compactly, we have that

(4.17)
$$
\int_{\Omega} |\nabla u_{\varepsilon}|^{p(x)-2} \nabla u_{\varepsilon} \nabla \varphi \, dx \to \int_{\Omega} |\nabla u|^{p(x)-2} \nabla u \nabla \varphi \, dx.
$$

On the other hand, we have

$$
|\nabla u_{\varepsilon}(x)|^{p_{\varepsilon}(x)-1} - |\nabla u_{\varepsilon}(x)|^{p(x)-1} = |\nabla u_{\varepsilon}(x)|^{b_{\varepsilon}(x)} \log(|\nabla u_{\varepsilon}(x)|)(p_{\varepsilon}(x)-p(x)),
$$

where $b_{\varepsilon}(x) = p_{\varepsilon}(x)\theta + (1 - \theta)p(x) - 1$ for some $0 < \theta < 1$. Therefore, using that $2^* = \infty$ and that $p_{\varepsilon} \to p$ uniformly, we obtain

(4.18)
$$
\int_{\Omega} (|\nabla u_{\varepsilon}|^{p_{\varepsilon}(x)-2} - |\nabla u_{\varepsilon}|^{p(x)-2}) \nabla u_{\varepsilon} \nabla \varphi \, dx \to 0.
$$

Then, using that $f_{\varepsilon} \to f$ in $L^{q(\cdot)}(\Omega)$, (4.16), (4.17) and the (4.18) we conclude that u is a solution of (1.1) .

Now, we consider the case $p \in \text{Lip}(\overline{\Omega})$. By Lemmas B.1 and B.2 there exists $p_{\varepsilon} \in C^1(\overline{\Omega})$ such that $|\Omega \setminus \Omega_0| < \varepsilon$ where

$$
\Omega_0 = \{ x \in \Omega \colon p_{\varepsilon}(x) = p(x) \text{ and } \nabla p_{\varepsilon}(x) = \nabla p(x) \}.
$$

We define f_{ε} as in (4.14). Then, the solution u_{ε} of (1.1) with p_{ε} and f_{ε} instead of p and f is bounded in $H^2(\Omega)$ by a constant independent of ε . Therefore there exist a subsequence still denoted $\{u_{\varepsilon}\}_{{\varepsilon \in (0,1]}}$ and $u \in H^2(\Omega)$ satisfying (4.15) .

Lastly, we prove that u is a solution of (1.1). Let $\varphi \in C_0^{\infty}(\Omega)$. By Hölder inequality, since $2^* = \infty$ and by (3) of Lemma B.2 we have

$$
\int_{\Omega\setminus\Omega_0} (|\nabla u_{\varepsilon}|^{p_{\varepsilon}(x)-2} - |\nabla u_{\varepsilon}|^{p(x)-2}) \nabla u_{\varepsilon} \nabla \varphi \, dx \n\leq C(\|\nabla u_{\varepsilon}\|_{L^{p_{\varepsilon}}(\Omega)} \|1\|_{L^{p_{\varepsilon}}(\Omega\setminus\Omega_0)} + \|\nabla u_{\varepsilon}\|_{L^{p}(\Omega)} \|1\|_{L^{p}(\Omega\setminus\Omega_0)}) \n\leq C\|u_{\varepsilon}\|_{H^{2}(\Omega)} (\|1\|_{L^{p_{\varepsilon}}(\Omega\setminus\Omega_0)} + \|1\|_{L^{p}(\Omega\setminus\Omega_0)}).
$$

Then, since $||u_{\varepsilon}||_{H^2(\Omega)}$ is bounded independent of ε and $|\Omega \setminus \Omega_0| < \varepsilon$ we obtain that

$$
\int_{\Omega\setminus\Omega_0}(|\nabla u_\varepsilon|^{p_\varepsilon(x)-2}-|\nabla u_\varepsilon|^{p(x)-2})\nabla u_\varepsilon\nabla\varphi\,dx\to 0.
$$

Therefore, since (4.16), (4.17) again hold, using that $f_{\varepsilon} \to f$ in $L^{q(\cdot)}(\Omega)$, and the above equation, we conclude that u is a solution of (1.1) .

5. The convex case

Lastly, we want to prove that the solution is in $H^2(\Omega)$ if we only assume that $\partial\Omega$ is convex. We want to remark here that this result generalize the one in Theorem 2.2 in [22] in two ways. In that paper the authors consider the case $p = constant$ and $q = 0$. Instead, we are allowed to cover the case where g is any function in $H^2(\Omega)$ and $p(x) \in \text{Lip}(\overline{\Omega})$.

Remark 5.1. Let Ω be a convex set and $p : \Omega \to [1, \infty)$ be log –continuous in $\overline{\Omega}$. Then, there exists a sequence $\{\Omega_m\}_{m\in\mathbb{N}}$ of convex subset of Ω with C² boundary such that $\Omega_m \subset \Omega_{m+1}$ for any $m \in \mathbb{N}$ and $|\Omega \setminus \Omega_m| \to 0$.

(1) Then, there exists a constant C depending on $p(x)$, $|\Omega|$ such that

$$
||v||_{L^{p(\cdot)}(\Omega_m)} \leq C||\nabla v||_{L^{p(\cdot)}(\Omega_m)} \quad \forall v \in W_0^{1,p(\cdot)}(\Omega_m),
$$

for any $m \in \mathbb{N}$. This follows by Theorem 3.3 in [21], using that $\Omega_m \subset \Omega_{m+1}$ for any $m \in \mathbb{N}$.

(2) The Lipschitz constants of Ω_m ($m \in \mathbb{N}$) are uniformly bounded (see Remark 2.3 in [22]). Therefore, the extension operators

$$
E_{1,m}: W^{1,p(\cdot)}(\Omega_m) \to W^{1,p(\cdot)}(\Omega)
$$
 and $E_{2,m}: H^2(\Omega_m) \to H^2(\Omega)$

define as Theorem 4.2 in [11] satisfy that $||E_{1,m}||$ and $||E_{2,m}||$ are uniformly bounded.

(3) By (2) and Corollary 8.3.2 in [12], there exists a constant C independent of m such that

$$
||v||_{L^{p^*(.)}(\Omega_m)} \leq C||v||_{W^{1,p(\cdot)}(\Omega_m)} \quad \forall v \in W^{1,p(\cdot)}(\Omega_m),
$$

for any $m \in \mathbb{N}$.

We want to remark that all the constants of the above inequalities are independent of p_1 (see Section 6 for the applications).

Proof of Theorem 1.2. We begin taking $\{\Omega_m\}_{m\in\mathbb{N}}$ as in Remark 5.1 and u_m the solution of

$$
\begin{cases}\n-\Delta_{p(x)} u_m = f & \text{in } \Omega_m, \\
u_m = g & \text{on } \partial \Omega_m.\n\end{cases}
$$

By Theorem 1.1, $u_m \in H^2(\Omega_m)$ for any $m \in \mathbb{N}$. Moreover, u_m solves

$$
\begin{cases}\nL^m u_m = a_{ij}^m(x) u_{m,x_ix_j} = a^m(x) & \text{in } \Omega_m, \\
u_m = g & \text{on } \partial \Omega_m,\n\end{cases}
$$

with

$$
a_{ij}^{m}(x) = \delta_{ij} + (p(x) - 2) \frac{u_{m,x_i}(x)u_{m,x_j}(x)}{|\nabla u_m(x)|^2},
$$

\n
$$
a^{m}(x) = \ln(|\nabla u_m(x)|) \langle \nabla u_m(x), \nabla p(x) \rangle + f(x) |\nabla u_m(x)|^{2-p(x)}.
$$

Then $v_m = u_m - g$ solves

$$
\begin{cases} L^m v_m = -L^m g + a^m(x) & \text{in } \Omega_m, \\ v_m = 0 & \text{on } \partial \Omega_m. \end{cases}
$$

Thus, using that $v_m \in H^2(\Omega_m) \cap H_0^1(\Omega_m)$ and since the coefficients $a_{ij}^m(x)$ are bounded independent of m , we can argue as in Theorem 2.2 in [22] and obtain, (5.19)

$$
||v_m||_{H^2(\Omega_m)} \le C||-L^mg+f|\nabla u_m|^{2-p(\cdot)} + \ln(|\nabla u_m|)|\nabla u_m||_{L^2(\Omega_m)}
$$

$$
\le C\left(|||\nabla u_m|^{2-p(\cdot)}||_{L^2(\Omega_m)} + ||\ln(|\nabla u_m|)|\nabla u_m||_{L^2(\Omega_m)} + 1\right)
$$

where the constant C is independent of m .

As in Lemma 4.1 we can prove, using Remark 5.1 (1) and (3), that the norms $\|\nabla u_m\|_{L^{p(\cdot)}(\Omega_m)}$ are uniformly bounded. Therefore, proceeding as in Theorem 4.2 we obtain

$$
(5.20) \qquad \qquad || \ln(|\nabla u_m|) |\nabla u_m||_{L^2(\Omega_m)} + ||f|\nabla u_m|^{2-p} ||_{L^2(\Omega_m)} \n\leq C \left(||\nabla u_m||_{L^{p'(\cdot)(1+s)}(\Omega_{1,m})}^{(1+s)/2} + ||\nabla u_m||_{L^{\gamma(\cdot)}(A_{2,m})}^{2-p_1} + 1 \right),
$$

with C independent of m , where

$$
\Omega_{1,m} = \{ x \in \Omega_m : |\nabla u_m(x)| > 1 \} \text{ and } A_{2,m} = \{ x \in \Omega_m : p(x) < 2 \}.
$$

Now, using Remark 5.1 (3) and (2), we have that for any $r > 1$ that

$$
||v_m||_{W^{1,r}(\Omega_m)} \le ||E_{2,m}v_m||_{W^{1,r}(\Omega)}
$$

(5.21)

$$
\le C||E_{2,m}v_m||_{H^2(\Omega)}
$$

$$
\le C||v_m||_{H^2(\Omega_m)}
$$

where C is independent of m .

Therefore, using (5.19) , (5.20) and (5.21) , we get

$$
||v_m||_{H^2(\Omega_m)} \leq C(||v_m||_{H^2(\Omega_m)}^{(1+s)/2} + ||v_m||_{H^2(\Omega_m)}^{2-p_1} + ||g||_{H^2(\Omega_m)}^{(1+s)/2} + ||g||_{H^2(\Omega_m)}^{2-p_1} + 1)
$$

$$
\leq C(||v_m||_{H^2(\Omega_m)}^{(1+s)/2} + ||v_m||_{H^2(\Omega_m)}^{2-p_1} + 1),
$$

where the constant C is independent of m. This proves that $\{\|v_m\|_{H^2(\Omega_m)}\}_{m\in\mathbb{N}}$ is bounded.

Now we have, as in the proof of Theorem 2.2 in [22], that there exist a subsequence still denote ${w_m}_{m \in \mathbb{N}}$ and a function $v \in H^2(\Omega) \cap H_0^1(\Omega)$ such that,

$$
v_m \to v \quad \text{strongly in } H^1(\Omega')
$$

$$
\Omega. \text{ Then } u = v + g \in H^2(\Omega) \text{ and}
$$

$$
u_m \to u
$$
 strongly in $H^1(\Omega')$

for any $\Omega' \subset\subset \Omega$. Thus, using (4.13), we have

(5.22)
$$
|\nabla u_m|^{p(x)-2} \nabla u_m \to |\nabla u|^{p(x)-2} \nabla u \quad \text{strongly in } L^{p'(\cdot)}(\Omega')
$$

for any $\Omega' \subset\subset \Omega$.

for any $\Omega' \subset \subset$

On the other hand, for any $\varphi \in C_0^{\infty}(\Omega)$ there exist m_0 such that for all $m \geq m_0$

$$
\int_{\Omega_m} |\nabla u_m|^{p(x)-2} \nabla u_m \nabla \varphi \, dx = \int_{\Omega_m} f \varphi \, dx.
$$

Therefore, using (5.22) we have that u is a weak solution of (1.1). \Box

Proof of Corollary 1.3. By the previous theorem we have that $u \in H^2(\Omega)$, then we can derive the equation (1.1) and obtain

$$
\begin{cases}\n-a_{ij}(x)u_{x_ix_j} = a(x) & \text{in } \Omega, \\
u = g & \text{on } \partial\Omega,\n\end{cases}
$$

where

$$
a_{ij}(x) = \delta_{ij} + (p(x) - 2) \frac{u_{x_i}(x) u_{x_j}(x)}{|\nabla u(x)|^2},
$$

\n
$$
a(x) = \ln(|\nabla u(x)|) \langle \nabla u(x), \nabla p(x) \rangle + f(x) |\nabla u(x)|^{2-p(x)}.
$$

Using that $f \in L^{q(\cdot)}(\Omega)$ with $q(x) \ge q_1 > 2$ and following the lines in the proof of Theorem 4.2, we have that $a(x) \in L^{s}(\Omega)$ with $s > 2$. Therefore, by Remark A.3, we have that $u \in C^{1,\alpha}(\overline{\Omega})$.

6. Comments

In the image processing problem it is of interest the case where p_1 is close to 1. By this reason, we are also interested in the dependence of the H^2 –norm on p_1 .

If $N = 2$, $g \in H^2(\Omega)$ and u_{ε} is the solution of (3.2), we have by Lemma A.1, (3.6) and (3.7), that there exists a constant C independent of p_1 and ε such that

$$
||u_{\varepsilon}||_{H^{2}(\Omega)} \leq \frac{C}{(p_{1}-1)^{\kappa}} \left(||a_{\varepsilon}||_{L^{2}(\Omega)} + ||g||_{H^{2}(\Omega)} \right),
$$

where $\kappa = 1$ if Ω is convex and $\kappa = 2$ if $\partial \Omega \in C^2$. Therefore, using that the Poincare's inequality and the embedding $W^{1,p(\cdot)}(\Omega) \hookrightarrow L^{p^*(\cdot)}(\Omega)$ hold in the case $p_1 = 1$ and following the lines of Theorem 1.1 and Theorem 1.2 we have that

$$
||u||_{H^2(\Omega)} \leq \frac{C}{(p_1-1)^{\kappa}},
$$

where the constant C is independent of p_1 .

Appendix A. Regularity results for elliptic linear equations WITH COEFFICIENTS IN L^{∞}

Let Ω be an bounded open subset of \mathbb{R}^2 and

$$
\mathcal{M}u = a_{ij}(x)u_{x_ix_j},
$$

such that $a_{ij} = a_{ji}$ and for any $\xi \in \mathbb{R}^N$

$$
(A.1) \qquad \qquad \lambda |\xi|^2 \le a_{ij}(x)\xi_i\xi_j \le \Lambda |\xi|^2,
$$

and

(A.2)
$$
M_1 \le a_{11}(x) + a_{22}(x) \le M_2
$$
 in Ω

where λ, Λ, M_1 and M_2 are positive constant.

In the next lemma, we will give a H^2 –bound for solutions of

(A.3)
$$
\begin{cases} \mathcal{M}u = f & \text{in } \Omega, \\ u = g & \text{on } \partial\Omega, \end{cases}
$$

In fact, the following result is proved in Theorem 37,III in [23], but it is not explicit the dependence of the bounds on the ellipticity and the L^{∞} −norm of $(a_{ij}(x))$. Then, following the proof of the mentioned theorem we can prove

Lemma A.1. Let Ω be a bounded domain in \mathbb{R}^2 , $f \in L^2(\Omega)$ and $g \in H^2(\Omega)$. Then, if u is a solution of (A.3) and $u \in H^2(\Omega)$ we have that

$$
||u||_{H^2(\Omega)} \leq \frac{C}{\lambda^{\kappa}} \left(||f||_{L^2(\Omega)} + ||g||_{H^2(\Omega)} \right),
$$

where $\kappa = 1$ if Ω is convex and $\kappa = 2$ if $\partial \Omega \in C^2$ and C is a constant independent of λ .

Proof. In this proof, we denote $u_{ij} = u_{x_i x_j}$ for all $i, j = 1, 2$ and C is a constant independent of λ .

First, we consider the case $q \equiv 0$. Using (A.1), we have that

$$
(a_{11}(x) + a_{22}(x))(u_{12}^2 - u_{11}u_{22}) = \sum_{i,j,k=1}^2 a_{ij}u_{ki}u_{kj} - \Delta u \sum_{ij=1}^2 a_{ij}u_{ij}
$$

$$
\geq \lambda \sum_{ik=1}^2 u_{ki}^2 - \Delta u f(x).
$$

Then, using Young's inequality, we get

$$
\frac{\lambda}{2(a_{11}(x) + a_{22}(x))} \sum_{ik=1}^{2} u_{ki}^2 \le \frac{4}{\lambda(a_{11}(x) + a_{22}(x))} f(x)^2 + u_{12}^2 - u_{11}u_{22},
$$

and by $(A.2)$, we have that

(A.4)
$$
\sum_{ik=1}^{2} u_{ki}^{2} \leq \frac{C}{\lambda^{2}} f(x)^{2} + \frac{C}{\lambda} (u_{12}^{2} - u_{11} u_{22}),
$$

Now, using (37.4) and (37.6) in [23], we have that for any $u \in H^2(\Omega)$

(A.5)
$$
\int_{\Omega} (u_{12}^2 - u_{11}u_{22}) dx = - \int_{\partial \Omega} \left(\frac{\partial u}{\partial \nu}\right)^2 \frac{H}{2} ds
$$

where H is the curvature of $\partial\Omega$. If Ω is convex, then $H \geq 0$ and therefore, using $(A.4)$ and $(A.5)$ we have that

(A.6)
$$
||D^2u||_{L^2(\Omega)} \leq \frac{C}{\lambda}||f||_{L^2(\Omega)}.
$$

In the general case, we can use the following inequality

(A.7)
$$
\int_{\partial\Omega} \left(\frac{\partial u}{\partial \nu}\right)^2 ds \le C \left((1+\delta^{-1}) \int_{\Omega} |\nabla u|^2 dx + \delta \int_{\Omega} \sum_{ik=1}^2 u_{ki}^2 dx \right)
$$

for any $\delta > 0$. See equation (37.6) of [23].

Then, by (A.4), (A.5), using that H is bounded and (A.7) (choosing δ properly) we arrive to

(A.8)
$$
\int_{\Omega} \sum_{ik=1}^2 u_{ki}^2 dx \leq \frac{C}{\lambda^2} \left(\int_{\Omega} f(x)^2 dx + \int_{\Omega} |\nabla u|^2 dx \right).
$$

On the other hand, using that $Lu = f$ in Ω , (A.1) and the Poincare's inequality, we have

(A.9)
$$
\|\nabla u\|_{L^2(\Omega)} \leq \frac{C}{\lambda} \|f\|_{L^2(\Omega)}.
$$

Therefore, by $(A.8)$ and $(A.9)$, we get

$$
||D^2u||_{L^2(\Omega)} \leq \frac{C}{\lambda^2} ||f||_{L^2(\Omega)}.
$$

Thus, by the last inequality, (A.9) and (A.6) the lemma is proved in the case $q=0$.

When g is any function in $H^2(\Omega)$ the lemma follows taking $v = u - g$. \Box

The following theorem is proved in Corollary 8.1.6 in [20].

Theorem A.2. Let Ω be a convex polygonal domain in \mathbb{R}^2 , M satisfying $(A.1)$ and $u \in H^2(\Omega) \cap H_0^1(\Omega)$ be a solution of $(A.3)$ with $g = 0$ and $f \in$ $L^p(\Omega)$ with $p > 2$. Then $\nabla u \in C^{\mu}(\overline{\Omega})$ for some $0 < \mu < 1$.

Remark A.3. Observe that the above Theorem holds also if we consider any $q \in W^{2,p}(\Omega)$, since we can take $v = u - q$ in $(A.3)$ and use that $W^{2,p}(\Omega) \hookrightarrow$ $C^{1,1-2/p}(\overline{\Omega})$.

Appendix B. Lipschitz Functions

Using the linear extension operator define in [14], we have the following lemma

Lemma B.1. Let Ω be a bounded open domain with Lipschitz boundary and $f \in \text{Lip}(\overline{\Omega})$. Then, there exists a function $\overline{f} : \mathbb{R}^N \to \mathbb{R}$ such that \overline{f} is a *Lipschitz function*, $\sup_{\mathbb{R}^N} f = \inf_{\overline{\Omega}} f$ and $\inf_{\mathbb{R}^N} f = \max_{\overline{\Omega}} f$.

Lemma B.2. Let $f : \mathbb{R}^N \to \mathbb{R}$ be Lipschitz function. Then for each $\varepsilon > 0$, there exists a C^1 function $f_{\varepsilon}: \mathbb{R}^N \to \mathbb{R}$ such that

- (1) $|\{x \in \mathbb{R}^N : f_{\varepsilon}(x) \neq f(x) \text{ or } Df_{\varepsilon}(x) \neq Df(x)\}| \leq \varepsilon.$
- (2) There exist a constant C depending only on N such that,

$$
||Df_{\varepsilon}||_{L^{\infty}(\mathbb{R}^N)} \leq C Lip(f).
$$

(3) If $1 < f_1 \leq f(x) \leq f_2$ in \mathbb{R}^N , we have

$$
1 < f_{\varepsilon}(x) \le f_2 + C \varepsilon^{\frac{1}{N}} \ \text{in} \ \mathbb{R}^N
$$

with C a constant depending only on N.

Proof. Items (1) and (2) follow by Theorem 1, pag. 251 in [16].

To prove (3), let as define

$$
\Omega_0 = \{ x \in \mathbb{R}^N \colon f_{\varepsilon}(x) = f(x) \text{ and } Df_{\varepsilon}(x) = Df(x) \}
$$

and let as suppose that there exist $x \in \mathbb{R}^N \setminus \Omega_0$ such that $f_{\varepsilon}(x) = f_2 + \delta$ with $\delta > 0$. If $x_0 \in \Omega_0$, by (2), we have

$$
CLip(f)|x - x_0| \ge f_{\varepsilon}(x) - f_{\varepsilon}(x_0) = f_2 + \delta - f(x_0) \ge \delta.
$$

Then $B_\rho(x) \subset \mathbb{R}^N \setminus \Omega_0$ where $\rho = \delta (CLip(f))^{-1}$ and using (1) we get $\delta \leq C \varepsilon^{1/N}$, for some constant C independent of ε .

Analogously we can prove the other inequality.

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